

A  
Geometrical  
Derivation  
of the  
**Formula**

$$\frac{d \tan \theta}{d\theta} = \sec^2 \theta$$

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In higher mathematics, most formulas for derivatives of trigonometric functions are proved either by using a direct method according to the definition of derivatives or by using an indirect method according to the operation rules of derivatives [1]. These methods appear to be dull and inflexible to readers. In this article, a geometrical method is given to derive the formula

$$\frac{d \tan \theta}{d\theta} = \sec^2 \theta .$$

Let's consider the geometry shown in Figure 1. Unit circle  $O$  is put in the Cartesian plane. The center of the unit circle  $O$  is located at the origin  $O$  and the circle  $O$  intersects the positive  $x$ -axis  $Ox$  at point  $D$ . The tangent line  $AD$  of the unit circle  $O$  is parallel to the  $y$ -axis with the contact point at  $D$ . Radial line  $OA$  intersects  $AD$  at point  $A$  with an angle  $\theta$  with respect to the positive  $x$ -axis  $Ox$ . Assuming an increment in  $\theta$  is  $\Delta\theta$  ( $\ll 1$ ), the radial line  $OA$  coincides with the radial line  $OC$  which intersects  $AD$  at point  $C$  and the increment in  $y$  is  $\overline{AC}$  denoted by  $\Delta y$ .

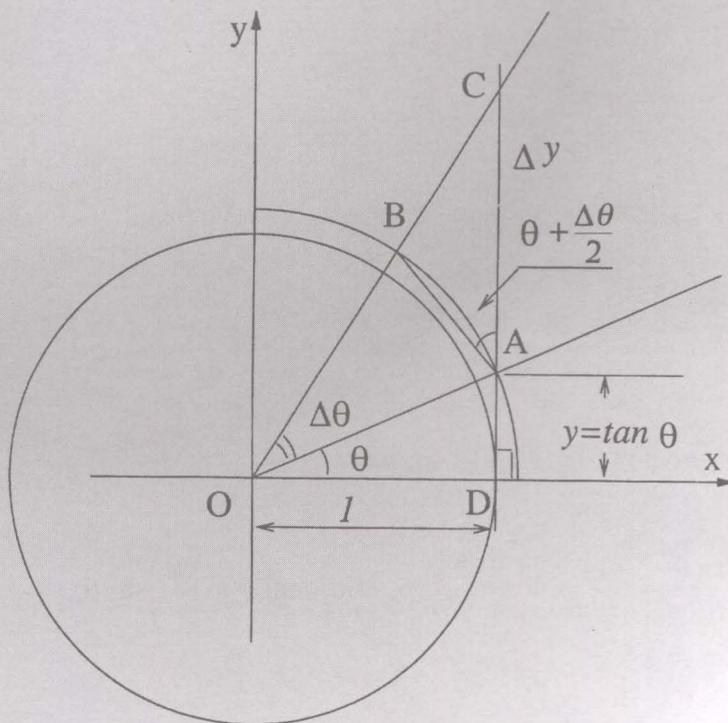


Figure 1. Geometry under consideration

In order to connect the unknown  $\Delta y$  with all the known data, we draw another arc  $AB$  with its center at  $O$  and radius equal to  $\overline{OA}$ . The arc  $AB$  intersects  $OA$  and  $OC$  at  $A$  and  $B$ , respectively.

From  $\triangle OAD$ , we know

$$y = \overline{AD} = \tan \theta \quad (1)$$

and

$$\overline{OA} = \sec \theta \quad (2)$$

according to the definition of trigonometric functions. Noticing that  $\Delta\theta \ll 1$ ,  $\triangle ABC$  can be approximated to a right triangle with  $\angle ABC \approx \pi/2$  and  $\angle BAC = \theta + \frac{\Delta\theta}{2}$ , and  $\overline{AB}$  can be approximated as follows:

$$\overline{AB} \approx AB = \Delta\theta \cdot \overline{OA}. \quad (3)$$

Substituting (2) into (3), we have

$$\overline{AB} \approx \Delta\theta \cdot \sec \theta. \quad (4)$$

Assuming  $\theta \neq (2k+1)\frac{\pi}{2}$  where  $k$  is an integer, we have  $\sec \theta \neq 0$  and

$$\frac{\Delta y}{\Delta\theta} = \frac{\Delta y \cdot \sec \theta}{\Delta\theta \cdot \sec \theta} \approx \frac{\Delta y}{\overline{AB}} \cdot \sec \theta = \sec\left(\theta + \frac{\Delta\theta}{2}\right) \cdot \sec \theta. \quad (5)$$

by using the express for  $\overline{AB}$  in (4). Finally, we have

$$\frac{d \tan \theta}{d\theta} = \frac{dy}{d\theta} = \lim_{\Delta\theta \rightarrow 0} \frac{\Delta y}{\Delta\theta} = \lim_{\Delta\theta \rightarrow 0} \sec\left(\theta + \frac{\Delta\theta}{2}\right) \sec \theta, \quad (6)$$

i.e.,

$$\frac{d \tan \theta}{d\theta} = \sec^2 \theta \quad (7)$$

which is just the formula we require. In the similar manner, one can easily prove

$$\frac{d \cot \theta}{d\theta} = -\csc^2 \theta.$$

## Reference

- [1] Donald Hartig, *On the Differentiation Formula for  $\sin \theta$* ,  
The American Mathematical Monthly, Vol. 96 (3) 1989, 252.